DISCIPLINE		SEMESTER	NAME OF THE TEACHING FACULTY		
ELECTRICAL		6ТН			
			MISS.SINDHUJA PANIGRA	HI(PTGF)	
SUBJECT: CSE		NO. OF DAYS PER WEEK CLASS ALLOTED : 05 SEMESTER FROM 04/02/2025 TO 17/05/2025			
ureve T	CLASS DAYS			NO. OF WEEKS 15 NOS.	
WEEKS	1ST		THEORY TOPICS		
1ST WEEK	2ND	Introduction to control system & Classification of Control system			
		Open loop system & Closed loop system and its comparison			
	3RD	Effects of Feed back			
	4TH	Standard test Signals(Step, Ramp, Parabolic, Impulse Functions)			
	5TH	Servomechanism			
2ND WEEK	1ST	Mathematical model of a system			
	2ND	Transfer Function & Impulse response			
	3RD	Properties, Advantages & Disadvantages of Transfer Function			
	4TH	Poles & Zeroes of transfer Function			
	5TH	Simple problems of transfer function of network			
3RD WEEK	1ST	Simple problems of transfer function of network			
	2ND	Mathematical modeling of Electrical Systems(R, L, C, Analogous systems)			
	3RD	Mathematical modeling of Electrical Systems(R, L, C, Analogous systems)			
	4TH	Components of Control System, Gyroscope			
	5TH	Synchros, Tachometer			
4TH WEEK	1ST	DC servomotors	The second of th	and the second	
	2ND	Ac Servomotors.			
	3RD	Block diagram algebra &signal flow graphs			
	4TH	Definition: Basic Elem	ents of Block Diagram	iliga kan digera iliya kan gara	
	5TH	Canonical Form of Closed loop Systems			
5TH WEEK	1ST	Rules for Block diagra	m reduction		
	2ND	Procedure for of Redu	uction of Block Diagram		
	3RD	Simple Problem for equivalent transfer function			
	4TH	Basic Definition in Signal Flow Graph & properties			
	5TH	Construction of Signal Flow graph from Block diagram			
6TH WEEK	1ST	Mason's Gain formula			
	2ND	Simple problems in Signal flow graph for network			
	3RD	Simple problems in Signal flow graph for network			
	4TH	Time response Analysis, Time response of control system			
	5TH	Standard test Signals(Step, Ramp, Parabolic, Impulse Functions)			
7TH WEEK	1ST	Time Response of firs	t order system		
	2ND	Time Response of first order system with Unit step response			
	3RD	Time Response of first order system with Unit impulse response			
	4TH	Time response of second order system to the unit step input			
	5TH	Time response specification			
	1ST	Derivation of expression for rise time, peak time, peak overshoot			
	2ND	Derivation of expression for settling time and steady state error			

8TH WEEK	3RD	Steady state error and error constants		
	4TH	Types of control system (see al.		
	5TH	Types of control system. [Steady state errors in Type-0, Type-1, Type-2 system] Effect of adding poles and zero to traver (
	1ST	Effect of adding poles and zero to transfer function. Response with P, PI, PD and PID controller.		
	2ND	Response with P, PI, PD and PID controller.		
9TH WEEK	3RD	Analysis of stability by root locous technique		
	4TH	Root locus concept.		
	5TH	Construction of root loci.		
	1ST	Rules for construction of the root locus.		
	2ND	Effect of adding poles and zeros to G(s) and H(s).		
10TH WEEK	3RD	solve numericals on root locous		
	4TH	solve numericals on root locous		
F	5TH	solve numericals on root locous		
	1ST	Frequency response analysis		
H	2ND	Correlation between time response and frequency response		
11TH WEEK	3RD	Polar plots		
	4TH	Polar plots		
	5TH	Bode plots		
y z	1ST	Bode plots		
	2ND	All pass and minimum phase system		
12TH WEEK	3RD	Computation of Gain margin and phase margin		
	4TH	Log magnitude versus phase plot		
	5TH	Closed loop frequency response		
	1ST	Nyquist Plot		
_	2ND	Principle of argument.		
13TH WEEK	3RD	Nyquist stability criterion.		
	4TH	Nyquist stability criterion.		
	5TH	Niquiet stability criterion applied to inverse polar plot.		
	1ST	Effect of addition of poles and zeros to G(S) H(S) on the shape of Niquist plot.		
+	2ND	Assessment of relative stability		
14TH WEEK	3RD	Constant M and N circle		
	4TH	Constant M and N circle		
F	5TH	Constant M and N circle		
	1ST	Nicholas chart		
-	2ND	Nicholas chart		
15TH WEEK	3RD	Nicholas chart		
-	4TH	Doubt clearing session		
	5TH	Doubt clearing session		

Control as (Chr. F. F. F. F. F. C.)

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